



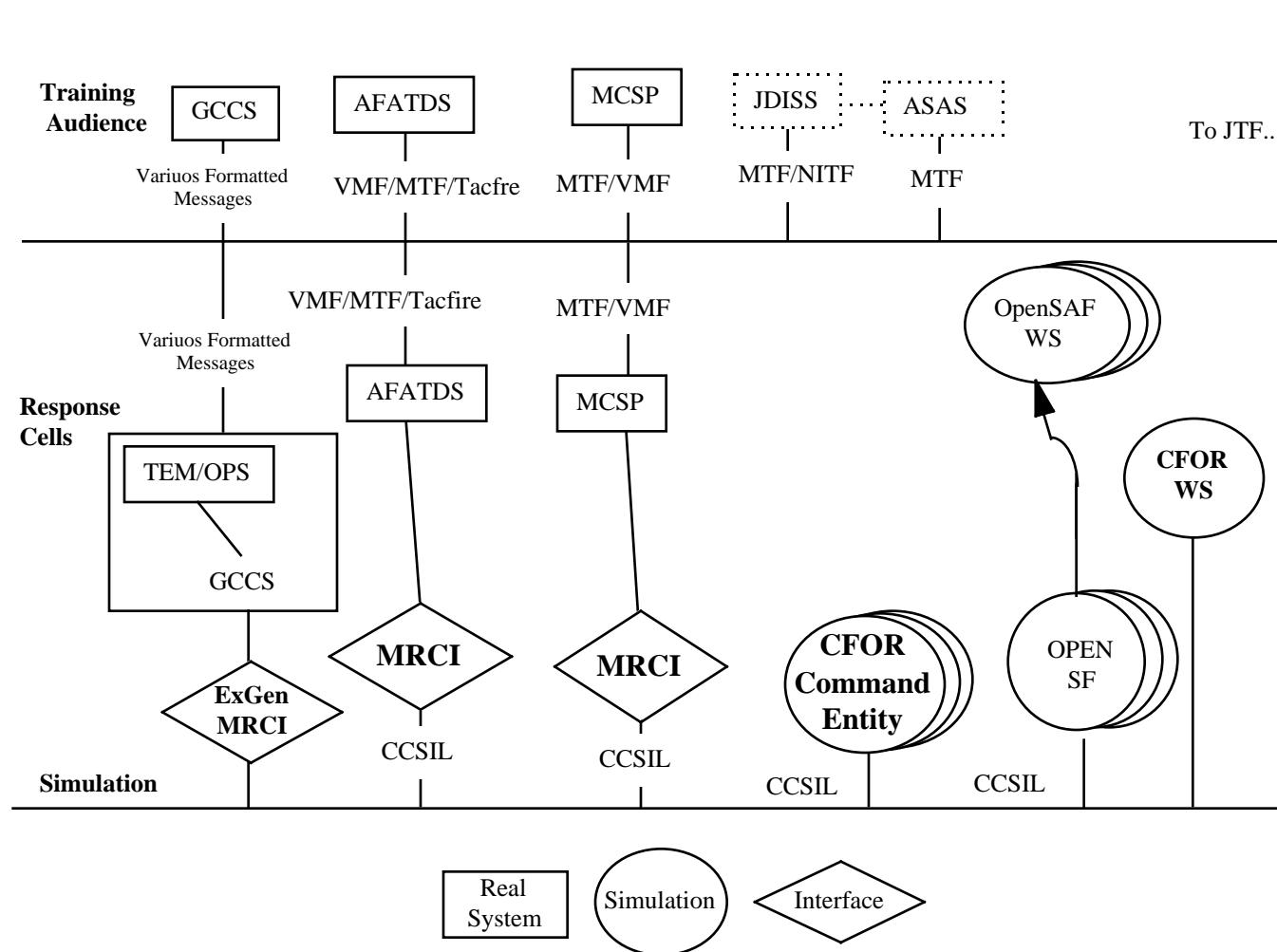
STOW MRCI Requirements Summary



- Compliance With STOW HLA - the Use of the STOW Simulation Support Framework (SSF) or the Provision of Equivalent Functionality
- Ability to communicate CCSIL messages via the SIOM/RTI OM
- Compliance With GCCS and DII Common Operating Environments
- Translation Between C4I System and Simulation Representations of C2 Information (CCSIL to /From USMTF, Link, VMF ...)
- Provide Translations Between C4I System and Simulation System Representations of Information, Including, but Not Limited to, Terrain, Weather, and Entity State
- GEO-registration handled inside MRCI (UTM <-> Lat/Long)
- Interfaces Must Be Portable To All Instantiations of C4I System (i.e. CTAPS Stand Alone vs. CTAPS in JMCIS vs. TBMCS implementation)
- STOW 97 should be the primary driver for MRCI in FY 97
 - Cooperative Development of GCCS Interface With STOW for Integration of TEM and EDSS Mission Planning Tools
 - CCSIL Message Sets Should Be Expanded to Support Additional Message/Data Transfer As Identified Within STOW-97 Requirement Documents
 - Other System Interfaces: JMCIS and JDISS are Top Priority

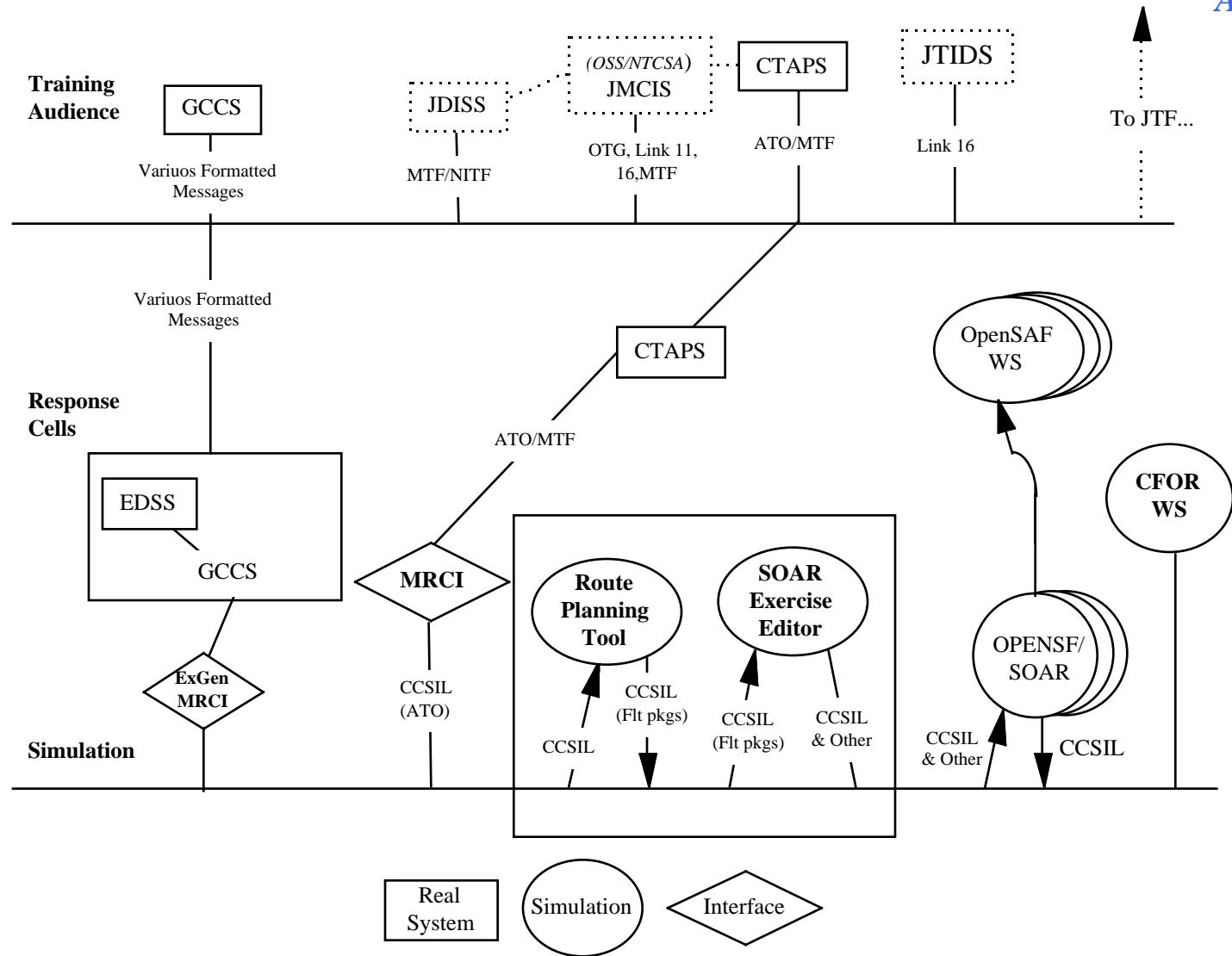


Army Interfaces



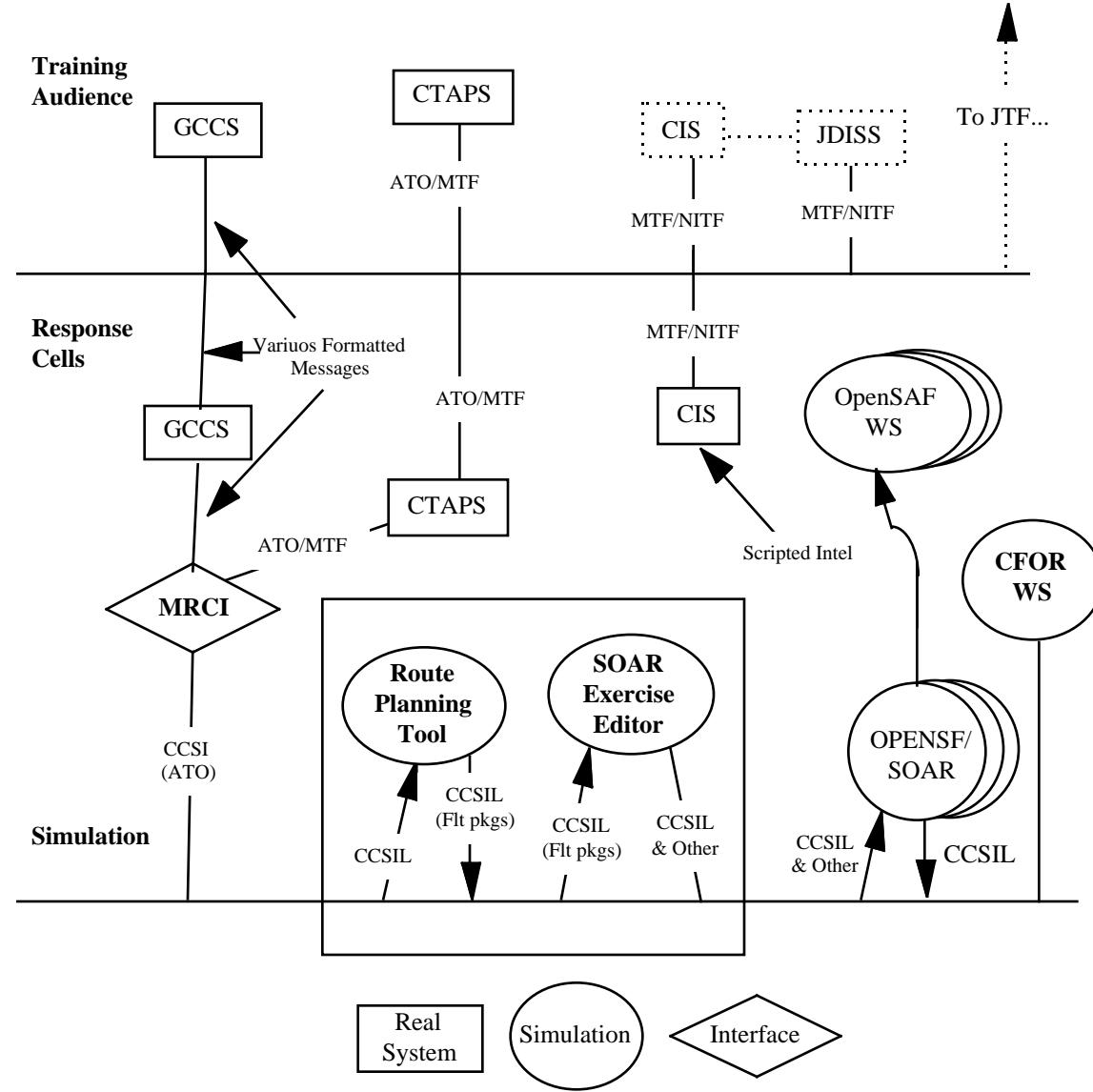


Navy Interfaces





Air Force Interfaces





Marine Corps Interfaces

